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IN THE CLAIMS

1. (currently amended) A method for controlling speed in a pulse-width-modulation-controlled motor powered by a load voltage source, said method comprising the steps of:

measuring the motor load voltage, wherein said step of measuring the motor load voltage further comprises utilizing at least one switching element to bypass a resistive element;  
and

setting pulse-width modulation duty cycles based on the measured voltage, wherein an average of frequencies of the pulse-width modulation duty cycles is a predetermined average pulse-width modulation frequency of the motor.

2. (original) A method in accordance with Claim 1 wherein said steps are sequentially executed and repeated automatically while the motor is in an on state.

3. (currently amended) ~~A method in accordance with Claim 1 wherein a supply voltage supplies the load voltage, said method further comprising the step of~~ A method for controlling speed in a pulse-width-modulation-controlled motor powered by a load voltage source, said method comprising the steps of:

measuring the motor load voltage, wherein a supply voltage provides the load voltage;

setting pulse-width modulation duty cycles based on the measured voltage, wherein an average of frequencies of the pulse-width modulation duty cycles is a predetermined average pulse-width modulation frequency of the motor; and

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diagnosing a motor functionality using a difference between the supply voltage and the load voltage;

4. (canceled)

5. (original) A method in accordance with Claim 3 wherein the supply voltage is unregulated.

6. (original) a method in accordance with Claim 3 wherein the supply voltage is direct current.

7. (previously presented) A method for controlling speed in a pulse-width-modulation-controlled motor powered by a load voltage, the load voltage supplied by a supply voltage, said method comprising the steps of:

diagnosing motor functionality using a difference between the supply voltage and the load voltage;

switching from motor functionality diagnosis to motor speed control; and

setting an average speed of the motor by superimposing sweep frequencies onto an average pulse-width frequency, the average pulse-width frequency being a predetermined average of the sweep frequencies.

8. (original) A method in accordance with Claim 7 wherein said step of diagnosing motor functionality comprises the step of using a pulse width modulation duty cycle of 100 percent.

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9. (original) A method in accordance with Claim 7 wherein said step of diagnosing motor functionality using a difference between the supply voltage and the load voltage comprises calculating power used by the motor in accordance with:

$$\frac{[(Upper\_A/D\_Reading)-(Lower\_A/D\_Reading)]^2}{R_{sense}}$$

where *Upper \_ A / D Reading* is the supply voltage measurement, *Lower \_ A / D \_ Reading* is the load voltage measurement, and *Rsense* is a resistance between measurement locations for *Upper \_ A / D \_ Reading* and *Lower \_ A / D \_ Reading*.

10. (original) A closed loop motor control system, said system comprising:
- a motor;
  - a power source;
  - a resistive element electrically coupling said motor to said power source;
  - at least one switching element electrically coupling said motor to said power source in parallel to said resistive element; and
  - a processor electrically connected to said switching element, said processor configured to:
    - determine a load voltage; and
    - set a pulse width modulation duty cycle based on the determined voltage.

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11. (original) A closed loop system in accordance with Claim 10 wherein said processor further configured to:

determine the load voltage while the motor is in an on state repeatedly automatically; and

set a pulse width modulation duty cycle based on the determined voltage while the motor is in an on state repeatedly automatically.

12. (original) A closed loop system in accordance with Claim 10 wherein said processor further configured to diagnose motor functionality.

13. (original) A closed loop system in accordance with Claim 12 wherein said processor further configured to diagnose motor functionality using a pulse width modulation duty cycle of 100 percent.

14. (original) A closed loop system in accordance with Claim 12 wherein said processor further configured to diagnose motor functionality by calculating power used by the motor in accordance with:

$$\frac{[(Upper\_A/D\_Reading)-(Lower\_A/D\_Reading)]^2}{R_{sense}}$$

where *Upper\_A/D\_Reading* is a supply voltage measurement, *Lower\_A/D\_Reading* is a load voltage measurement, and *R<sub>sense</sub>* is a resistance between measurement locations for *Upper\_A/D\_Reading* and *Lower\_A/D\_Reading*.

15. (original) A system in accordance with Claim 10 wherein said power source comprises an unregulated voltage supply.

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16. (original) A system in accordance with Claim 15 wherein said unregulated voltage supply comprises an unregulated DC voltage supply.

17. (previously presented) A method for operating a motor configured to operate at a variable average speed under pulse-width modulation control, said method comprising the steps of:

energizing the motor; and

setting an average speed by superimposing sweep frequencies onto an average pulse-width modulation frequency, the average pulse-width modulation frequency being a predetermined average of the sweep frequencies.

18. (previously presented) A method in accordance with Claim 17 wherein said step of setting an average speed further comprises the step of setting an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a monotonically increasing waveform.

19. (previously presented) A method in accordance with Claim 17 wherein said step of setting an average speed further comprises the step of setting an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a monotonically decreasing waveform.

20. (previously presented) A method in accordance with Claim 17 wherein said step of setting an average speed further comprises the step of setting an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a random waveform centered around the average pulse-width modulation frequency.

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21. (previously presented) A method in accordance with Claim 17 wherein said step of setting an average speed further comprises the step of setting an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a monotonically increasing waveform with a low value approximately 20% below the average and a high value approximately 20% above the average.

22. (previously presented) A method in accordance with Claim 17 wherein said step of setting an average speed further comprises the step of setting an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a monotonically decreasing waveform with a low value approximately 20% below the average and a high value approximately 20% above the average.

23. (previously presented) A method in accordance with Claim 17 wherein said step of setting an average speed further comprises the step of setting an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a random waveform centered around the average pulse-width modulation frequency with a low value approximately 20% below the average and a high value approximately 20% above the average.

24. (previously presented) A method in accordance with Claim 17 wherein said step of setting an average speed further comprises the step of setting an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a monotonically increasing waveform with a low value at least approximately 5% below the average and a high value at least approximately 5% above the average.

25. (previously presented) A method in accordance with Claim 17 wherein said step of setting an average speed further comprises the step of setting an average speed by

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superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a monotonically decreasing waveform with a low value at least approximately 5% below the average and a high value at least approximately 5% above the average.

26. (previously presented) A method in accordance with Claim 17 wherein said step of setting an average speed further comprises the step of setting an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a random waveform centered around the average pulse-width modulation frequency with a low value at least approximately 5% below the average and a high value at least approximately 5% above the average.

27. (currently amended) A motor comprising:

a housing;

a stator mounted in said housing, said stator comprising a stator bore;

a rotor rotatably mounted at least partially within said stator bore; and

a processor electrically connected to at least one of said stator and said rotor, said processor configured to:

determine a load voltage; and

~~set pulse-width modulation duty cycles based on the determined voltage,~~  
~~wherein an average of frequencies of the pulse width modulation duty cycles is a predetermined~~  
~~average pulse width modulation frequency of the motor~~set an average speed of the motor by  
superimposing sweep frequencies onto an average pulse-width frequency, the average pulse-  
width frequency being a predetermined average of the sweep frequencies.

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28. (previously presented) A motor in accordance with Claim 27 wherein said processor further configured to diagnose motor functionality.

29. (previously presented) A motor in accordance with Claim 28 wherein said processor further configured to diagnose motor functionality by calculating power use in accordance with:

$$\frac{[(Upper\_A/D\_Reading)-(Lower\_A/D\_Reading)]^2}{R_{sense}}$$

where *Upper \_ A / D \_ Reading* is a supply voltage measurement, *Lower \_ A / D \_ Reading* is a load voltage measurement, and *Rsense* is a resistance between measurement locations for *Upper \_ A / D \_ Reading* and *Lower \_ A / D \_ Reading*.

30. (previously presented) A motor comprising:

a housing;

a stator mounted in said housing, said stator comprising a stator bore;

a rotor rotatably mounted at least partially within said stator bore; and

a processor electrically connected to at least one of said stator and said rotor, said processor configured to set an average speed by superimposing sweep frequencies onto an average pulse-width modulation frequency, wherein the average pulse-width modulation frequency is a predetermined average of the sweep frequencies.

31. (previously presented) A motor in accordance with Claim 30 wherein said processor further configured to set an average speed by superimposing a sweep frequency range



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onto an average pulse-width modulation frequency forming a monotonically increasing waveform.

32. (previously presented) A motor in accordance with Claim 30 wherein said processor further configured to set an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a monotonically decreasing waveform.

33. (previously presented) A motor in accordance with Claim 30 wherein said processor further configured to set an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a random waveform centered around the average pulse-width modulation frequency.

34. (previously presented) A motor in accordance with Claim 30 wherein said processor further configured to set an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a monotonically increasing waveform with a low value approximately 20% below the average and a high value approximately 20% above the average.

35. (previously presented) A motor in accordance with Claim 30 wherein said processor further configured to set an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a monotonically decreasing waveform with a low value approximately 20% below the average and a high value approximately 20% above the average.

36. (previously presented) A motor in accordance with Claim 30 wherein said processor further configured to set an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a random waveform centered around

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the average pulse-width modulation frequency with a low value approximately 20% below the average and a high value approximately 20% above the average.

37. (previously presented) A motor in accordance with Claim 30 wherein said processor further configured to set an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a monotonically increasing waveform with a low value at least approximately 5% below the average and a high value at least approximately 5% above the average.

38. (previously presented) A motor in accordance with Claim 30 wherein said processor further configured to set an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a monotonically decreasing waveform with a low value at least approximately 5% below the average and a high value at least approximately 5% above the average.

39. (previously presented) A motor in accordance with Claim 30 wherein said processor further configured to set an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a random waveform centered around the average pulse-width modulation frequency with a low value at least approximately 5% below the average and a high value at least approximately 5% above the average.

40. (previously presented) A refrigerator comprising:

- a housing;
- a freezer section at least partially within said housing;
- a fresh food section at least partially within said housing;

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a motor at least partially within said housing; and

a processor electrically connected to said motor, said processor configured to set an average speed of the motor by superimposing sweep frequencies onto an average pulse-width modulation frequency, wherein the average pulse-width modulation frequency is a predetermined average of the sweep frequencies.

41. (previously presented) A refrigerator in accordance with Claim 40 wherein said processor further configured to set an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a monotonically increasing waveform.

42. (previously presented) A refrigerator in accordance with Claim 40 wherein said processor further configured to set an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a monotonically decreasing waveform.

43. (previously presented) A refrigerator in accordance with Claim 40 wherein said processor further configured to set an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a random waveform centered around the average pulse-width modulation frequency.

44. (previously presented) A refrigerator in accordance with Claim 40 wherein said processor further configured to set an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a monotonically increasing waveform with a low value approximately 20% below the average and a high value approximately 20% above the average.

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45. (previously presented) A refrigerator in accordance with Claim 40 wherein said processor further configured to set an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a monotonically decreasing waveform with a low value approximately 20% below the average and a high value approximately 20% above the average.

46. (previously presented) A refrigerator in accordance with Claim 40 wherein said processor further configured to set an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a random waveform centered around the average pulse-width modulation frequency with a low value approximately 20% below the average and a high value approximately 20% above the average.

47. (previously presented) A refrigerator in accordance with Claim 40 wherein said processor further configured to set an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a monotonically increasing waveform with a low value at least approximately 5% below the average and a high value at least approximately 5% above the average.

48. (previously presented) A refrigerator in accordance with Claim 40 wherein said processor further configured to set an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a monotonically decreasing waveform with a low value at least approximately 5% below the average and a high value at least approximately 5% above the average.

49. (previously presented) A refrigerator in accordance with Claim 40 wherein said processor further configured to set an average speed by superimposing a sweep frequency range onto an average pulse-width modulation frequency forming a random waveform

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centered around the average pulse-width modulation frequency with a low value at least approximately 5% below the average and a high value at least approximately 5% above the average.

50. (currently amended) A refrigerator comprising:

a housing;

a freezer section at least partially within said housing;

a fresh food section at least partially within said housing;

a motor at least partially within said housing; and

a processor electrically connected to said motor, said processor configured to:

determine a load voltage; and

~~set pulse width modulation duty cycles based on the determined voltage;~~  
~~wherein an average of frequencies of the pulse width modulation duty cycles is a predetermined~~  
~~average of pulse width modulation frequency of the motor~~  
set an average speed of the motor by  
superimposing sweep frequencies onto an average pulse width frequency, the average pulse-  
width frequency being a predetermined average of the sweep frequencies.

51. (previously presented) A refrigerator in accordance with Claim 50 wherein said processor further configured to diagnose motor functionality.

52. (previously presented) A motor in accordance with Claim 51 wherein said processor further configured to diagnose motor functionality by calculating power use in accordance with:

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$$\frac{[(Upper\_A/D\_Reading)-(Lower\_A/D\_Reading)]^2}{R_{sense}}$$

where *Upper \_ A / D \_ Reading* is a supply voltage measurement, *Lower \_ A / D \_ Reading* is a load voltage measurement, and *R<sub>sense</sub>* is a resistance between measurement locations for *Upper \_ A / D \_ Reading* and *Lower \_ A / D \_ Reading*.